

## LECTURE 12

### DC Generators: Steady State-I

The material covered in this lecture will be as follows:

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- 1) Equivalent Circuit of DC generators
- 2) Classification of DC Machines..
- 3) Performance equations

At the end of this lecture you should be able to:

- ⇒ Represent a DC machine by an equivalent circuit.  
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Understand how to use performance equations to calculate voltage and current in a DC generator.  
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#### 1. DC Machine Classifications

DC machines are classified according the method of excitation or supply of the field winding  
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**a. Separately excited machines:** the field winding (excitation) receives its supply from a separate source.

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**b. Self excited machines: the field winding is excited from the machine itself.**

The self excited machines are classified further depending on the method of connection to the armature winding

1. Shunt connected: field winding is connected across (shunt or parallel) the armature.  
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2. Series connected: field winding is connected in series with the armature.  
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3. Compound connected: two field windings are used. One is connected in shunt across the armature while the second is in series with the armature.

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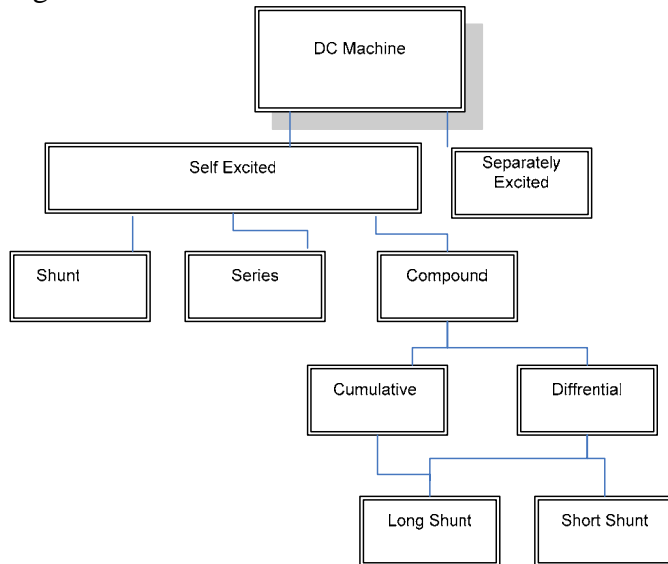
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Further classifications of the compound machine are:

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1. Long shunt: The shunt field is across both the armature and series field.  
Long shunt: The shunt field is across both the armature and series field.
2. Short Shunt: The shunt field is across the armature only followed by the series field.  
Short Shunt: The shunt field is across the armature only followed by the series field.

Figure 1 shows a Chart of the classification of the DC machines.



## 2. Equivalent Circuit of DC Machines

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2. The field circuit is represented by a winding that generates the magnetic field and a resistance connected in series. The field winding has resistance  $R_f$ .

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You recall that in lecture 12 we developed two equations for voltage and torque.

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The generated voltage is give by

$$E = K_a \phi_m \omega \quad (1)$$

Equation 1 shows the voltage generated is function of the magnetic flux and the speed of rotation.  
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The torque is given by

$$T \Leftrightarrow k \phi I \quad (2)$$

Equation 2 shows that the machine torque is function of the magnetic flux and the current drawn by the machine.

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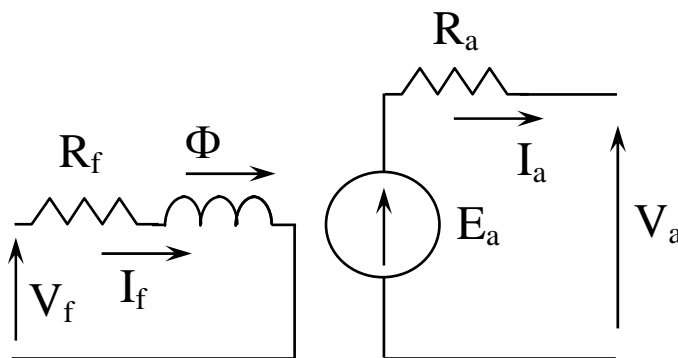
In this lecture we shall concentrate on the DC generator and its steady state performance  
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- By referring to figure 2, we can see that the magnetic field is generated by the field current  $I_f$ .
- The flux  $\phi$  is proportional to the field current.

$$\phi = k_f I_f \quad (3)$$

The  $K_f$  factor is calculated from the magnetic circuit using Amperes Law  
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Figure 2 show the equivalent circuit of DC machines



**Figure 2 Equivalent Circuit of a DC Machine**

- The flux  $\phi$  is proportional to the field current.

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$$\phi = k_f I_f$$

- The armature generated voltage is give by

$$E_a = K_a \phi_m \omega = K I_f \omega \quad (3)$$

Where  $E_a$  = armature generated voltage

$K_a$  = machine constant

$K$  = modified machine constant

The question is "What is the machine constant and how to determine it

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In order to define the machine constant, it is important to understand few points.

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We will derive the generated voltage in slight different manner.  
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The armature winding is made of many conductors  
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The conductors are arranged in coils. The coils are arranged in a number of parallel paths according to the method of winding.

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There are two types of windings: lap and wave windings  
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The lap winding is arranged such that the number of parallel paths is always equal to the number of poles.

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The wave winding is arranged such that the number of parallel paths is always equal to 2 irrespective of the number of poles.

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Let us define the following variables  
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Z= no. of armature conductors

P= no. of poles

a= no. parallel paths

= 2 for wave winding

= P for lap winding.

$\phi$  = flux per pole

N = speed in rpm

The flux cut by one conductors in one rotation =  $\phi P$

The flux cut by one conductors in N rotations =  $\phi PN$

The flux cut per second by one conductors =  $\frac{\phi PN}{60}$

Number of conductors in series =  $\frac{Z}{a}$

The flux cut per second by  $\frac{Z}{a}$  conductors =  $\frac{\phi PN}{60} \left(\frac{Z}{a}\right)$

This is the voltage generated in the armature E =  $\frac{\phi PN}{60} \left(\frac{Z}{a}\right)$

Let us express the speed in radian per second  $\omega = \frac{2\pi N}{60}$

Thus the voltage generated in the armature E =  $\frac{\phi P \omega}{2\pi} \left(\frac{Z}{a}\right)$

The relations is re-arranged such that  $E = \left(\frac{ZP}{2\pi a}\right)\phi\omega$

Finally, the armature voltage  $E = K_a \phi\omega$

Where  $K_a = \text{machine constant} = \frac{ZP}{2\pi a}$

### Example 1

Find the voltage induced in a DC machine that has flux per pole = 20 mWb. It has 4 poles and it is rotating at 1800 rpm. The machine winding is lap wound.

### Solution

For lap winding the number of parallel paths  $a=4$

$$\omega = \frac{2\pi N}{60} = \frac{2\pi \times 1800}{60} = 188.48 \text{ rad / sec}$$

$$\text{Where } K_a = \frac{ZP}{2\pi a} = \frac{800 \times 4}{2\pi \times 4} = 127.323$$

The armature induced voltage  $E = K_a \phi\omega = 127.323 \times 20 \times 10^{-3} \times 188.48 = 479.96 \text{ V}$

The relationship between the generated and the terminal voltages is given by  
**The relationship between the generated and the terminal voltages is given by**

$$E_a = V_a + I_a R_a \quad (4)$$

Where

$V_a$  = terminal voltage

$I_a$  = armature current

$R_a$  = armature resistance

In addition, the field voltage is related to the voltage by equation 5.

$$V_f = I_f R_f \quad (5)$$

Where

$V_f$  = field voltage

$I_f$  = field current

$R_f$  = field resistance

### Example 2

Find the terminal voltage of a separately excited DC generator as illustrated in figure 8 with following data:

$V_f = 240$  volts

$R_f = 120$  Ohms

$I_a = 80$  A

$R_a = 0.02$  Ohms

$N = 1800$  rpm

$K' = \text{modified machine constant} = 1.5 \text{ V-sec / A}$

### Solution

The speed in radian per second

$$\omega = \frac{2\pi N}{60} = \frac{2\pi \times 1800}{60} = 188.48 \text{ rad / sec}$$

$$I_f = \frac{V_f}{R_f} = \frac{240}{120} = 2A$$

$$E_a = KI_f \omega = 1.5 \times 2 \times 188.49 = 565.48V$$

The terminal voltage is given by

$$V_a = E_a - I_a R_a = 565.48 - 80 \times 0.02 = 563.88V$$

### 3. Types of DC Machines

The connection of the armature circuit to the field winding is dictated by the type of DC Machine.

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#### 1. Separately excited machine (Figure 3)

- The armature winding supplies the load.
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- 
- The field winding is supplied by a separate DC source whose voltage is variable.
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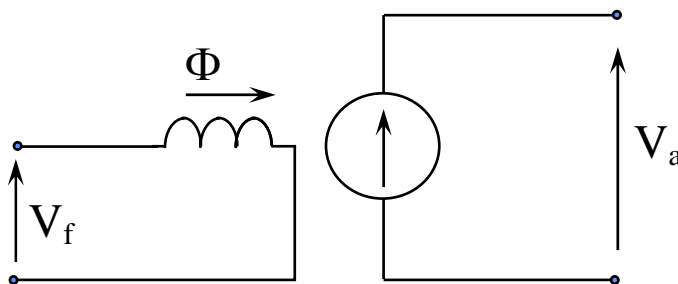


Figure 3 Separately Excited Machine

#### 2. Shunt DC Machine (Figure 4)

The armature and field windings are connected in parallel.

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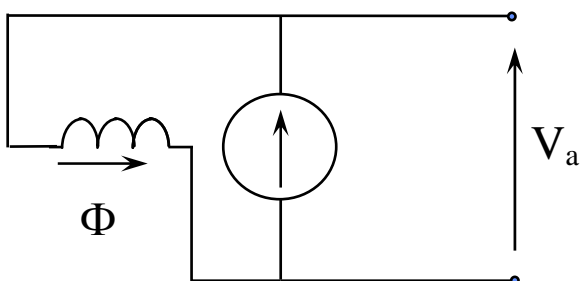


Figure 4 Shunt DC Machine

#### 3. Series DC Machine (Figure 5)

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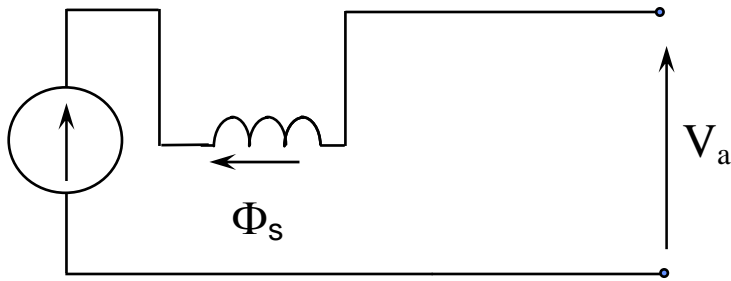


Figure 5 Series DC Machine

4. **Compound DC machine.**

The machine has two field windings: One connected in series; the other in parallel.

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a. **Short Shunt :** The shunt field is across the armature only followed by the series field.

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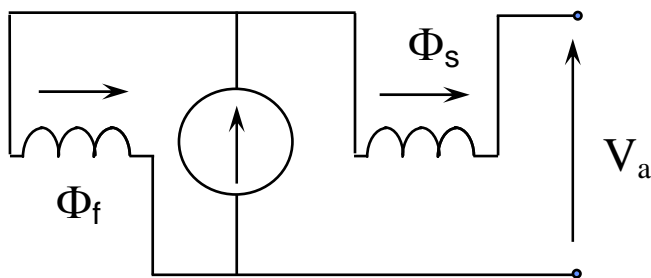


Figure 6 Short Shunt Compound s DC Machine

b. **Long Shunt:** The shunt field is across both the armature and series field.

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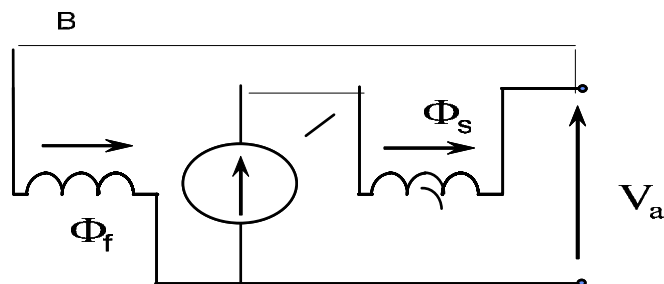


Figure 7 Long Shunt Compound DC Machine